

Practice Problem Set #2 Solutions

1. Determine the unilateral Laplace transform of the following signals:

(a) $x(t) = u(t - 2)$

(b) $x(t) = u(t + 2)$

(c) $x(t) = e^{-2t}u(t + 1)$

(d) $x(t) = e^{2t}u(-t + 2)$

(e) $x(t) = \sin(\omega_0 t)$

(f) $x(t) = u(t) - u(t - 2)$

(g) $x(t) = \begin{cases} \sin(\pi t), & 0 < t < 1 \\ 0, & \text{otherwise} \end{cases}$

(a) $x(t) = u(t - 2)$

$$\begin{aligned} X(s) &= \int_{0^-}^{\infty} x(t)e^{-st} dt \\ &= \int_{0^-}^{\infty} u(t - 2)e^{-st} dt \\ &= \int_2^{\infty} e^{-st} dt \\ &= \frac{e^{-2s}}{s} \end{aligned}$$

(b) $x(t) = u(t + 2)$

$$\begin{aligned} X(s) &= \int_{0^-}^{\infty} u(t + 2)e^{-st} dt \\ &= \int_{0^-}^{\infty} e^{-st} dt \\ &= \frac{1}{s} \end{aligned}$$

(c) $x(t) = e^{-2t}u(t + 1)$

$$\begin{aligned}
X(s) &= \int_{0^-}^{\infty} e^{-2t} u(t+1) e^{-st} dt \\
&= \int_{0^-}^{\infty} e^{-t(s+2)} dt \\
&= \frac{1}{s+2}
\end{aligned}$$

(d) $x(t) = e^{2t} u(-t+2)$

$$\begin{aligned}
X(s) &= \int_{0^-}^{\infty} e^{2t} u(-t+2) e^{-st} dt \\
&= \int_{0^-}^2 e^{t(2-s)} dt \\
&= \frac{e^{2(2-s)} - 1}{2-s}
\end{aligned}$$

(e) $x(t) = \sin(\omega_o t)$

$$\begin{aligned}
X(s) &= \int_{0^-}^{\infty} \frac{1}{2j} (e^{j\omega_o t} - e^{-j\omega_o t}) e^{-st} dt \\
&= \frac{1}{2j} \left[\int_{0^-}^{\infty} e^{t(j\omega_o - s)} dt - \int_{0^-}^{\infty} e^{-t(j\omega_o + s)} dt \right] \\
&= \frac{1}{2j} \left[\frac{-1}{j\omega_o - s} - \frac{1}{j\omega_o + s} \right] \\
&= \frac{\omega_o}{s^2 + \omega_o^2}
\end{aligned}$$

(f) $x(t) = u(t) - u(t-2)$

$$\begin{aligned}
X(s) &= \int_{0^-}^2 e^{-st} dt \\
&= \frac{1 - e^{-2s}}{s}
\end{aligned}$$

$$(g) x(t) = \begin{cases} \sin(\pi t), & 0 < t < 1 \\ 0, & \text{otherwise} \end{cases}$$

$$\begin{aligned} X(s) &= \int_{0^-}^1 \frac{1}{2j} (e^{j\pi t} - e^{-j\pi t}) e^{-st} dt \\ &= \frac{\pi(1 + e^{-s})}{s^2 + \pi^2} \end{aligned}$$

2. Use the Laplace transform tables and properties to obtain the Laplace transform of the following:

$$(a) x(t) = \frac{d}{dt} \{te^{-t}u(t)\}$$

$$(b) x(t) = tu(t) * \cos(2\pi t)u(t)$$

$$(c) x(t) = t^3u(t)$$

$$(d) x(t) = u(t-1) * e^{-2t}u(t-1)$$

$$(e) x(t) = \int_0^t e^{-3\tau} \cos(2\tau) d\tau$$

$$(f) x(t) = t \frac{d}{dt} (e^{-t} \cos(t)u(t))$$

$$(a) x(t) = \frac{d}{dt} \{te^{-t}u(t)\}$$

$$a(t) = te^{-t}u(t) \xleftrightarrow{\mathcal{L}_u} A(s) = \frac{1}{(s+1)^2}$$

$$x(t) = \frac{d}{dt} a(t) \xleftrightarrow{\mathcal{L}_u} X(s) = \frac{s}{(s+1)^2}$$

$$(b) x(t) = tu(t) * \cos(2\pi t)u(t)$$

$$a(t) = tu(t) \xleftrightarrow{\mathcal{L}_u} A(s) = \frac{1}{s^2}$$

$$b(t) = \cos(2\pi t)u(t) \xleftrightarrow{\mathcal{L}_u} \frac{s}{s^2 + 4\pi^2}$$

$$\begin{aligned} x(t) = a(t) * b(t) &\xleftrightarrow{\mathcal{L}_u} X(s) = A(s)B(s) \\ X(s) &= \frac{1}{s^2(s^2 + 4\pi^2)} \end{aligned}$$

$$(c) \ x(t) = t^3 u(t)$$

$$\begin{aligned} a(t) = tu(t) &\xleftrightarrow{\mathcal{L}_u} A(s) = \frac{1}{s^2} \\ b(t) = -ta(t) &\xleftrightarrow{\mathcal{L}_u} B(s) = \frac{d}{ds} A(s) = \frac{-2}{s^3} \\ x(t) = -tb(t) &\xleftrightarrow{\mathcal{L}_u} X(s) = \frac{d}{ds} B(s) = \frac{6}{s^4} \end{aligned}$$

$$(d) \ x(t) = u(t-1) * e^{-2t} u(t-1)$$

$$\begin{aligned} a(t) = u(t) &\xleftrightarrow{\mathcal{L}_u} A(s) = \frac{1}{s} \\ b(t) = a(t-1) &\xleftrightarrow{\mathcal{L}_u} B(s) = \frac{e^{-s}}{s} \\ c(t) = e^{-2t} u(t) &\xleftrightarrow{\mathcal{L}_u} C(s) = \frac{1}{s+2} \\ d(t) = e^{-2} c(t-1) &\xleftrightarrow{\mathcal{L}_u} D(s) = \frac{e^{-(s+2)}}{s+2} \\ x(t) = b(t) * d(t) &\xleftrightarrow{\mathcal{L}_u} X(s) = B(s)D(s) \\ X(s) &= \frac{e^{-2(s+1)}}{s(s+2)} \end{aligned}$$

$$(e) \ x(t) = \int_0^t e^{-3\tau} \cos(2\tau) d\tau$$

$$\begin{aligned} a(t) = e^{-3t} \cos(2t)u(t) &\xleftrightarrow{\mathcal{L}_u} A(s) = \frac{s+3}{(s+3)^2+4} \\ \int_{-\infty}^t a(\tau) d\tau &\xleftrightarrow{\mathcal{L}_u} \frac{1}{s} \int_{-\infty}^{0^-} a(\tau) d\tau + \frac{A(s)}{s} \\ X(s) &= \frac{s+3}{s((s+3)^2+4)} \end{aligned}$$

$$(f) \ x(t) = t \frac{d}{dt} (e^{-t} \cos(t)u(t))$$

$$\begin{aligned} a(t) = e^{-t} \cos(t)u(t) &\xleftrightarrow{\mathcal{L}_u} A(s) = \frac{s+1}{(s+1)^2+1} \\ b(t) = \frac{d}{dt} a(t) &\xleftrightarrow{\mathcal{L}_u} B(s) = \frac{s(s+1)}{(s+1)^2+1} \\ x(t) = tb(t) &\xleftrightarrow{\mathcal{L}_u} X(s) = -\frac{d}{ds} B(s) \\ X(s) &= \frac{-s^2-4s-2}{(s^2+2s+2)^2} \end{aligned}$$

3. Use the tables of transforms and properties to determine the time signals that correspond to the following bilateral Laplace transforms:

(a) $X(s) = e^{s^2} \frac{1}{s+2}$ with ROC $\text{Re}(s) < -2$

(b) $X(s) = \frac{d^2}{ds^2} \left(\frac{1}{s-3} \right)$ with ROC $\text{Re}(s) > 3$

(c) $X(s) = s \left(\frac{1}{s^2} - \frac{e^{-s}}{s^2} - \frac{e^{-2s}}{s} \right)$ with ROC $\text{Re}(s) < 0$

(d) $X(s) = s^{-2} \frac{d}{ds} \left(\frac{e^{-3s}}{s} \right)$ with ROC $\text{Re}(s) > 0$

(a) $X(s) = e^{5s} \frac{1}{s+2}$ with ROC $\text{Re}(s) < -2$

(left-sided)

$$A(s) = \frac{1}{s+2} \xleftarrow{\mathcal{L}} a(t) = -e^{-2t}u(-t)$$

$$X(s) = e^{5s}A(s) \xleftarrow{\mathcal{L}} x(t) = a(t+5) = -e^{-2(t+5)}u(-(t+5))$$

(b) $X(s) = \frac{d^2}{ds^2} \left(\frac{1}{s-3} \right)$ with ROC $\text{Re}(s) > 3$

(right-sided)

$$A(s) = \frac{1}{s-3} \xleftarrow{\mathcal{L}} a(t) = e^{3t}u(t)$$

$$X(s) = \frac{d^2}{ds^2}A(s) \xleftarrow{\mathcal{L}} x(t) = t^2e^{3t}u(t)$$

(c) $X(s) = s \left(\frac{1}{s^2} - \frac{e^{-s}}{s^2} - \frac{e^{-2s}}{s} \right)$ with ROC $\text{Re}(s) < 0$

(left-sided)

$$x(t) = \frac{d}{dt} (-tu(-t) + tu(-t-1) + u(-t-2))$$

$$x(t) = -u(-t) + u(-t-1) - \delta(t+2)$$

(d) $X(s) = s^{-2} \frac{d}{ds} \left(\frac{e^{-3s}}{s} \right)$ with ROC $\text{Re}(s) > 0$

(right-sided)

$$A(s) = \frac{1}{s} \xleftarrow{\mathcal{L}} a(t) = u(t)$$

$$B(s) = e^{-3s}A(s) \xleftarrow{\mathcal{L}} b(t) = a(t-3) = u(t-3)$$

$$C(s) = \frac{d}{ds}B(s) \xleftarrow{\mathcal{L}} c(t) = -tb(t) = -tu(t-3)$$

$$D(s) = \frac{1}{s} \xleftarrow{\mathcal{L}} d(t) = \int_{-\infty}^t c(\tau)d\tau$$

$$\xleftarrow{\mathcal{L}} d(t) = -\int_3^t \tau d\tau = -\frac{1}{2}(t^2 - 9)$$

$$X(s) = \frac{1}{s}D(s) \xleftarrow{\mathcal{L}} x(t) = \int_{-\infty}^t d(\tau)d\tau$$

$$\xleftarrow{\mathcal{L}} x(t) = -\frac{1}{2} \int_3^t (\tau^2 - 9)d\tau$$

$$\xleftarrow{\mathcal{L}} x(t) = \left[-\frac{1}{6}(t^3 - 27) + \frac{9}{2}(t-3) \right] u(t-3)$$

4. Evaluate the frequency-domain representations of the following signals:

(a) $x(t) = e^{-2t}u(t - 3)$

(b) $x(t) = e^{-4|t|}$

(c) $x(t) = te^{-t}u(t)$

(d) $x(t) = \sum_{m=0}^{\infty} a^m \delta(t - m), |a| < 1$

(a) $x(t) = e^{-2t}u(t - 3)$

$$\begin{aligned} X(j\omega) &= \int_{-\infty}^{\infty} x(t)e^{-j\omega t} dt \\ &= \int_3^{\infty} e^{-2t}e^{-j\omega t} dt \\ &= \frac{e^{-3(2+j\omega)}}{2 + j\omega} \end{aligned}$$

(b) $x(t) = e^{-4|t|}$

$$\begin{aligned} X(j\omega) &= \int_{-\infty}^{\infty} e^{-4|t|}e^{-j\omega t} dt \\ &= \int_0^{\infty} e^{-4t}e^{-j\omega t} dt + \int_{-\infty}^0 e^{4t}e^{-j\omega t} dt \\ &= \frac{8}{16 + \omega^2} \end{aligned}$$

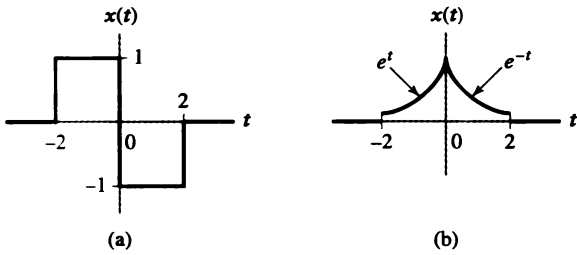
(c) $x(t) = te^{-t}u(t)$

$$\begin{aligned} X(j\omega) &= \int_0^{\infty} te^{-t}e^{-j\omega t} dt \\ &= \frac{1}{(1 + j\omega)^2} \end{aligned}$$

(d) $x(t) = \sum_{m=0}^{\infty} a^m \delta(t - m), |a| < 1$

$$\begin{aligned} X(j\omega) &= \int_0^{\infty} \left(\sum_{m=0}^{\infty} a^m \delta(t - m) \right) e^{-j\omega t} dt \\ &= \sum_{m=0}^{\infty} (ae^{-j\omega})^m \\ &= \frac{1}{1 - ae^{-j\omega}} \end{aligned}$$

5. Evaluate the frequency-domain representations of the shown signals:



(a) $x(t) = u(t+2) - 2u(t) + u(t-2)$ and evaluate Fourier transforms from table. Alternatively:

$$\begin{aligned} X(j\omega) &= \int_{-2}^0 e^{-j\omega t} dt - \int_0^2 e^{-j\omega t} dt \\ &= \frac{2 \cos(\omega) - 2}{j\omega} \end{aligned}$$

$$X(j\omega) = \begin{cases} \frac{2 \cos(\omega) - 2}{j\omega} & \omega \neq 0 \\ 0 & \omega = 0 \end{cases}$$

(b) $x(t) = \exp(-|t|) (u(t+2) - u(t-2))$ and evaluate from tables and use convolution property. Alternatively:

$$\begin{aligned} X(j\omega) &= \int_{-2}^0 e^t e^{-j\omega t} dt + \int_0^2 e^{-t} e^{-j\omega t} dt \\ &= \frac{1 - e^{-(1-j\omega)2}}{1 - j\omega} + \frac{1 - e^{-(1+j\omega)2}}{1 + j\omega} \\ &= \frac{2 - 2e^{-2} \cos(2\omega) + 2\omega e^{-2} \sin(2\omega)}{1 + \omega^2} \end{aligned}$$

6. Use the Fourier transform tables and properties to obtain the Fourier transform of the following signals:

(a) $x(t) = \sin(2\pi t) e^{-t} u(t)$

(b) $x(t) = t e^{-3t} u(t)$

(c) $x(t) = \left[\frac{2 \sin(3\pi t)}{\pi t} \right] \left[\frac{\sin(2\pi t)}{\pi t} \right]$

(d) $x(t) = \frac{d}{dt} (t e^{-2t} \sin(t) u(t))$

(e) $x(t) = \int_{-\infty}^t \frac{\sin(2\pi\tau)}{\pi\tau} d\tau$

(f) $x(t) = e^{-t+2} u(t-2)$

(g) $x(t) = \left(\frac{\sin(t)}{\pi t} \right) * \frac{d}{dt} \left[\left(\frac{\sin(2t)}{\pi t} \right) \right]$

(a) $x(t) = \sin(2\pi t)e^{-t}u(t)$

$$\begin{aligned} x(t) &= \sin(2\pi t)e^{-t}u(t) \\ &= \frac{1}{2j}e^{j2\pi t}e^{-t}u(t) - \frac{1}{2j}e^{-j2\pi t}e^{-t}u(t) \end{aligned}$$

$$\begin{aligned} e^{-t}u(t) &\xleftrightarrow{FT} \frac{1}{1+j\omega} \\ e^{j2\pi t}u(t) &\xleftrightarrow{FT} S(j(\omega-2\pi)) \\ X(j\omega) &= \frac{1}{2j} \left[\frac{1}{1+j(\omega-2\pi)} - \frac{1}{1+j(\omega+2\pi)} \right] \end{aligned}$$

(b) $x(t) = te^{-3|t-1|}$

$$\begin{aligned} e^{-3|t|} &\xleftrightarrow{FT} \frac{6}{9+\omega^2} \\ s(t-1) &\xleftrightarrow{FT} e^{-j\omega}S(j\omega) \\ tw(t) &\xleftrightarrow{FT} j\frac{d}{d\omega}W(j\omega) \\ X(j\omega) &= j\frac{d}{d\omega} \left[e^{-j\omega} \frac{6}{9+\omega^2} \right] \\ &= \frac{6e^{-j\omega}}{9+\omega^2} - \frac{12j\omega^{-j\omega}}{(9+\omega^2)^2} \end{aligned}$$

(c) $x(t) = \left[\frac{2\sin(3\pi t)}{\pi t} \right] \left[\frac{\sin(2\pi t)}{\pi t} \right]$

$$\begin{aligned} \frac{\sin(Wt)}{\pi t} &\xleftrightarrow{FT} \begin{cases} 1 & \omega \leq W \\ 0, & \text{otherwise} \end{cases} \\ s_1(t)s_2(t) &\xleftrightarrow{FT} \frac{1}{2\pi}S_1(j\omega) * S_2(j\omega) \\ X(j\omega) &= \begin{cases} 5 - \frac{|\omega|}{\pi} & \pi < |\omega| \leq 5\pi \\ 4 & |\omega| \leq \pi \\ 0 & \text{otherwise} \end{cases} \end{aligned}$$

(d)

$$\begin{aligned} x(t) &= \frac{d}{dt}te^{-2t}\sin(t)u(t) \\ &= \frac{d}{dt}te^{-2t}u(t) \frac{e^{jt} - e^{-jt}}{2j} \end{aligned}$$

$$te^{-2t}u(t) \xleftrightarrow{FT} \frac{1}{(2+j\omega)^2}$$

7. Replace the time variable " t " with the frequency variable " Ω " in all signals in problems 4, 5 and 6 and repeat to obtain the inverse Fourier transform of these signals.

Solution: Use the duality property to do that in one step.